

WEST Search History

DATE: Wednesday, April 18, 2007

| Hide? | <u>Set</u> <u>Name</u> | <u>Query</u> | <u>Hit</u> <u>Count</u> |
|--------------------------|---|--|----------------------------|
| | <i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i> | | |
| <input type="checkbox"/> | L23 | controller and L22 | 10 |
| <input type="checkbox"/> | L22 | l21 and correction | 11 |
| <input type="checkbox"/> | L21 | "off-line programming" and l4 | 26 |
| <input type="checkbox"/> | L20 | recording and L19 | 277 |
| <input type="checkbox"/> | L19 | (run or execut\$5) and L18 | 1269 |
| <input type="checkbox"/> | L18 | L16 and L17 | 1796 |
| <input type="checkbox"/> | L17 | software or program\$4 and control\$3 and robot\$6 and L16 | 762807 |
| <input type="checkbox"/> | L16 | (700/245 318/568.11 901/15).ccls. | 3432 |
| <input type="checkbox"/> | L15 | computer and L14 | 168 |
| <input type="checkbox"/> | L14 | search\$3 and L13 | 177 |
| <input type="checkbox"/> | L13 | record\$3 and L12 | 346 |
| <input type="checkbox"/> | L12 | (motion or displacement of trajectory) and L11 | 653 |
| <input type="checkbox"/> | L11 | control software and L10 | 1110 |
| <input type="checkbox"/> | L10 | software same robot\$6 | 6899 |
| <input type="checkbox"/> | L9 | L8 and replacement | 0 |
| <input type="checkbox"/> | L8 | 5268837.pn. | 2 |
| <input type="checkbox"/> | L7 | "center or gravity" and L6 | 1 |
| <input type="checkbox"/> | L6 | orientation or position or claculat\$5 and L5 | 5925561 |
| <input type="checkbox"/> | L5 | controller and L4 | 1114 |
| <input type="checkbox"/> | L4 | (flexure or turn or beind or fold or cascade or sequence) and (program\$4 or software) and L3 | 1662 |
| <input type="checkbox"/> | L3 | (700/245,248,248,258,259 or 318/568.1,568.2 or 901/1).ccls. | 3536 |
| <input type="checkbox"/> | L2 | controller and L1 | 49 |
| <input type="checkbox"/> | L1 | (flexure or turn or beind or fold or cascade or sequence) and correction (program\$4 or software) and robot\$6 | 80 |

END OF SEARCH HISTORY